# bc330SBX <br> Time Code Translator 8500-0004 

User's Guide

Rev B
(June 30, 2000)

## bc330SBX <br> TIME CODE TRANSLATOR

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## ADDENDUM A

OUTPUTS

## A. 0 J2 SERIAL RS-422 DIFFERENTIAL OUTPUT

A serial RS-422 differential output is available on the edge connector labeled "P1" pin 22 and pin 24. A twisted pair wires can be used with P1-22 and P1-24. This output port can be used for diagnostic purposes. The bc330sbx broadcasts time, measured code period, code detection status, code search status, software version and date code, AGC slice level, and control byte information. Data is sent at 9600 baud, eight data bits, one stop bit, no parity. Each line is terminated by a carriage return (0DH) and a line feed (0AH).

The Tx(-) signal will drive most RS-232 interfaces such as a serial port to a PC. The data pacing signals RTS, CTS, DSR and DTR may need to be jumpered depending on the specific terminal emulation software in use.

## A. 1 BC330SBX RS-422 SERIAL OUTPUT MESSAGES

When a valid time code signal is being decoded, a packet of data is sent every second, about $1 / 2$ second after the 1 pps signal occurs. The following are examples of message data when decoding the respective time code signals, real time clock and other time sources:

## Initialization Message

```
SLAMR bc330sbx x.x dd/mm/yr
initialization complete
control bytes 0/1/2 = XX/XX
hb period remainder = XXXX XXXX
```


## Decoding Modulated Time Code

```
(Time code type) { irigb, 2137}
lev = XX {X represents a hexadecimal digit}
dif = XXXX
buf2 ddd hh:mm:ss
etim ddd hh:mm:ss :: :: ::
```


## Searching For Time Code With Time Code Select Register Set For Autodetect

```
checking (time code type) {Modulated time code: irigb, 2137}
lev = cannot find (time code type)
```


## Time Code Error Message

```
decode error !!
```


## Flywheeling Message

```
flywheeling !!
buf2 ddd hh:mm:ss
etim ddd hh:mm:ss :: :: ::
```


## Notes

- "lev" is a hex representation of the "slice" level of a modulated time code. It is used to determine whether a cycle is a high or low cycle.
- "dif" is hexadecimal representation of the time code period measurement. It is used to scale the internal time. The "dif" value reflects the difference between the internal crystal and the external time signal.
- No control codes or commands are accepted by the user through the RS-422 port.
- The RS-422 messages were provided primarily for diagnostic purposes. The user, however, may use the data to obtain time externally from the board. Once a valid time code is being decoded, time/message data is broadcast once each second about $1 / 2$ second after the 1 pps signal. The time being broadcast, following the "buf2" label, is valid at the rising edge of the preceding 1pps pulse.


## CHAPTER ONE

## INTRODUCTION

### 1.0 SCOPE

This manual provides the information necessary to interface the bc330SBX Time Code Translator to a host environment which conforms to the SBX mechanical and electrical specifications defined in document ANSI/IEEE Standard 959-1988.

### 1.1 FUNCTIONAL DESCRIPTION

The bc330SBX Time Code Translator has been designed to decode the following time codes:
IRIG B - OS 1.0
2137 - OS 1.0
The bc330SBX has been designed to translate time codes at near real time rates, and to accept a wide range of input amplitudes and signal to noise ratios. A sophisticated 'flywheel' algorithm makes input code loss transparent to the user.

The bc330SBX module can be directed to automatically identify and translate an input code or to search only for a specified code.

The bc330SBX measures the period of the source time code to determine the rate offset of the module oscillator. This measurement is performed at a resolution of 0.5 microseconds. If the source time code is lost, the bc330SBX will continue to maintain time to the accuracy of 0.5 microseconds per second or approximately $\pm 5$ parts in 10E7. Temperature changes or other factors, which would cause the bc330SBX crystal to drift, will degrade this accuracy. Experience in typical laboratory environments shows that drift rates of less than a part in 1E6 are consistently achieved during periods of code loss.

The bc330SBX always assumes that the input code is accurate with respect to code rate, and 'locks' the flywheel algorithm to the measured code period.

The bc330SBX provides a hardware event strobe input which will 'log' the time of an external event to 0.5 microsecond accuracy. The CMOS logic input may be configured under software control as either positive or negative edge triggered. The occurrence of an event may be determined by polling, or the event may be programmed to generate an interrupt. Bus time requests (requests for current time) are also processed to an accuracy of 0.5 microseconds. The time is referenced to the time at which a specific bus address location is written. Both the current time and the event time output are in a packed $B C D$ format.

In addition to BCD time of day, the bc330SBX outputs a one pulse per second (PPS) CMOS strobe, and a programmable CMOS pulse rate. The one PPS strobe may be advanced or retarded by up to $\pm 1$ millisecond in steps of 0.5 microseconds to compensate for propagation delay effects.

### 1.2 ELECTRICAL DESCRIPTION

The bc330SBX conforms to the specifications of ANSI/IEEE Standard 959-1988, Section Three. The logic family used in the bc330SBX is CMOS, and the specific requirements for the signals in Table Six of the ANSI document are met.

Table 1-1 provides the actual electrical characteristics of the bc330SBX by signal type for the SBX bus connector (P2).

Table 1-2 provides similar data for the card edge connector signals (P1).
Table 1-3 defines the signals on the card edge connector.

Table 1-1
DC Specifications (BUS I/O - P2)

| Signal | IOL (ma) | IOH(ma) | C(pf) |
| :--- | :---: | :---: | :---: |
| MA0-MA2 | - | - | 12 |
| MCS0-MCS1 | - | - | 12 |
| MDACK | Not Connected. | Not Connected. |  |
| MD0-MD7 | 16 | -4 | 12 |
| IORD*, IOWRT* | - | - | 12 |
| MWAIT* | 16 | -4 | 12 |
| MDRQT | Not Connected. | Not Connected. |  |
| TDMA | Not Connected. | Not Connected. |  |
| RESET | Not Connected. | Not Connected. |  |
| MCLK | Not Connected. | Not Connected. |  |
| MINTR0, MINTR1 | 1.6 | -0.8 | 12 |
| OPT0, OPT1 | Not Connected. | Not Connected. |  |
| MPST* | Grounded. | Grounded |  |
| +5 VDC (power) | $100 m a ~ @ 25^{\circ} \mathrm{C}$ | 100 ma @ $25^{\circ} \mathrm{C}$ |  |

Table 1-2
DC Specifications (Edge Connector - P1)

| Signal | IOL (ma) | IOH(ma) | R(OHMS) |
| :--- | :---: | :---: | :---: |
| TIMECODE IN | - | - | 10 k |
| Rate Variance $= \pm 2 \%$ of nominal Amplitude 100mV to 5V peak to peak. |  |  |  |
| IP CLOCK OUT | 1 | -1 |  |
| AUXA2, AUGA1 | $<3>$ | - | 10 k |
| TX(-) | 8 | -8 |  |
| PULSE1 | 1.6 | -0.8 |  |
| 1PPS | 1.6 | -0.8 |  |
| MOS1, SCK | $<2>$ Do Not Use. | Do Not Use. |  |

Table 1-3
Signal Definitions (Edge Connector - P1)

| Pin Number | Signal/Function |
| :---: | :--- |
| ODD | GROUND |
| 2 | Timecode Input |
| 4 | Event Input (TTL/CMOS) |
| 6 | SCK |
| 8 | 1PPS Output (CMOS) |
| 10 | Pulse Rate 1 Out (CMOS) |
| 12 | SYNCH <4> |
| 14 | AUXA1 Input (0 to 5 VDC) |
| 16 | AUXA2 Input (0 to 5 VDC) |
| 18 | 10 kHz Timecode Clock <1> |
| 20 | MOSI <2> |
| 22 | TX(+) Serial Out + |
| 24 | TX(-) Serial Out - |
| 26 | MISO <2> |

<1> The 10 kHz clock is phase locked to the input time code when present, free-running otherwise.
<2> SCK, MOSI, and MISO support high speed serial I/O used in conjunction with Datum time code generators and video time inserters.
<3> Auxiliary analog inputs. Each channel is sampled at 8 bit resolution at an effective rate of 1PPS.
<4> SYNCH is a logic ' 1 ' when time code is detected and a logic ' 0 ' when flywheeling.

### 1.3 MECHANICAL DESCRIPTION

The bc330SBX conforms to the specifications of a single-wide expansion module as defined in ANSI/IEEE Standard 959-1988, Figure 18. The SBX connector conforms to Table Seven and Figure 24 of the ANSI document.

A threaded non-conducting spacer is provided with each bc330SBX module for mounting to the hose baseboard. A 26 pin connector which mates to the card edge connector is also provided with each module. This connector is a solder-less ribbon cable type.

### 1.4 LEVEL OF COMPLIANCE

The bc330SBX module has an IEEE 959 I/O compliance of D81.
D8 represents an 8 bit module. The ' I ' designation indicates that the WAIT* signal line is used. A wait state is only needed when the baseboard is polling the module address corresponding to the 'data ready flag.' A memory contention can occur if the bc330SBX processor is attempting to write to this location while it is being accessed by the baseboard.

No other memory operations require a wait state. The baseboard need not support MWAIT* if the host software is designed to poll the 'data ready flag' twice in succession to circumvent the possible memory contention.

## ADDRESS SPACE

### 2.0 CONTROL ADDRESS SPACE

The bc330SBX module has a chip select address range as illustrated in Figure 3 of ANSI/IEEE Standard 959-1988. The module address space of the bc330SBX may be modeled as an array of 16 bytes. The lower 8 bytes are selected by MCS0* and the upper 8 bytes are selected by MCS1*.

The bc330SBX software design allocates the lower 8 bytes to data transfer operations, and the upper 8 bytes to control data. In this Section and in Section 2.1, all addresses will be referenced as an offset from the base address, the first address in the 16 byte block. Table 2-1 defines the control functions by address offset.

Table 2-1
Control Functions VS Address Offset

| Offset | Default | Functions |
| :---: | :---: | :---: |
| 08H | 00H | Timecode Select $0=$ Auto detect. $42 \mathrm{H}=$ IRIG B only. <br> $43 \mathrm{H}=2137$ only (OS 1.1 or >). |
| 09H | 00H | Mask Register <br> $\mathrm{X} 0 \mathrm{H}=$ Event Capture disabled. <br> $\mathrm{X} 1 \mathrm{H}=$ Capture on rising edges. <br> $\mathrm{X} 2 \mathrm{H}=$ Capture on falling edges. <br> $\mathrm{X} 3 \mathrm{H}=$ Capture on both edges. <br> $\mathrm{X}=0 \quad$ Do not assert INTRO. <br> X=1 Assert MINTR0. |
| 0AH | 00 H <Note> | Status Register (read only) <br> X1H = Decoding IRIG B. <br> X3H = Decoding 2137. <br> $\mathrm{X}=0 \quad$ Timecode present. <br> $X=1 \quad$ Flywheeling. |
| 0BH | 00H | Pulse Rate Control <br> $00 \mathrm{H}=$ Pulse rate disabled. <br> $01 \mathrm{H}=$ Pulse enabled. |
| 0CH | 07H | Heartbeat Rate msbyte. |
| 0DH | D0H | Heartbeat Rate lsbyte. |
| 0EH | 00H | Propagation Delay msbyte. |
| 0FH | 00H | Propagation Delay lsbyte. |

<Note> Also set to 00 H by <initialization> command.

All of the control data bytes are in read/write RAM and may be accessed at any time. The status byte is the only data byte written to by the bc330SBX. All other bytes are considered read only. Likewise, it makes no sense for the baseboard to write data to the status byte location.

The baseboard may write to the control data at any time. Whether or not the control data is used varies as a function of data type. The heartbeat rate is used by the bc330SBX at the end of every pulse period. All other data bytes are only read during the execution of an initialization command. (See Section 2.1.)

On power on (pon) and when a <reset> command is executed, the control data is initialized to the indicated default values.

It is often useful to generate a periodic pulse/interrupt (heartbeat) which is synchronized to the time source signal. The bc330SBX has the ability to generate heartbeat pulses/interrupts between a 302000 Hz rate. The heartbeat rate register determines the rate of the pulses/interrupts (in pulses per second). Following a change to the heartbeat rate registers, the user must 'initialize' the bc330SBX.

The bc330SBX achieves synchronization of the heartbeats to the time source by computing the heartbeat pulse/interrupt period by dividing the time code period programmed heartbeat rate. The bc330SBX does the heartbeat period calculations in response to the 'initialize' command and at power on. The bc330SBX must be decoding time code or 'flywheeling' with a valid time code period to insure accurate heartbeat synchronization.

### 2.1 DATA TRANSFER ADDRESS SPACE

The data transfer address space consists of a sequence of eight bytes starting at the base address. This address space is accessed by MCSO*. The first seven bytes are dedicated to data and the last byte at offset 07 H is reserved as a command byte. This byte is also referred to as a 'data ready flag byte' when the baseboard is operating in a polled response mode.

The baseboard requests specific data from the bc330SBX by writing a coded request to offset 07 H . The baseboard must then wait for the command byte to be modified by the bc330SBX firmware to indicate that the requested data is available at offset locations 00 H through 06 H . The data format is defined in this section.

Note: Polling rates of the command register must not exceed 500 kHz .

The following command bytes have been defined for OS 1.0. Additional command bytes may be added in future versions of the bc330SBX firmware.

| Com | ready |  | data |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
| byte | flag | offset | bits 7-4 | / | bits 3-0 |

<Requests current time of day. Request time logged as the time when 80 H was written to offset 07 H .>

| $80 \mathrm{H} \quad 00 \mathrm{H}$ | 0 | / | seconds tens | 1 | seconds units |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | 1 | / | minutes tens | 1 | minutes units |
|  | 2 | / | hours tens | 1 | hours units |
|  | 3 | / | days tens | 1 | days units |
|  | 4 | / | DH1 DH0 0 C20 | 1 | C19 C18 C17 C16 |
|  | 5 | 1 | C07 C06 C05 C04 | 1 | C03 C02 C01 C00 |
|  | 6 | 1 | C15 C14 C13 C12 | 1 | C11 C10 C09 C08 |

C20-C00 $=$ Binary 0.5 microsecond count.
$\mathrm{DH} 1-\mathrm{DH} 0=$ Days of hundreds value $(0,1,2,3)$.
<Request last logged event time. Event time logged on programmed edge, positive or negative or both.>
$81 \mathrm{H} \quad 01 \mathrm{H}$ offsets 0-6 same as above
<Clear event capture. Event capture is disabled after each event until the command is executed.>

| $82 \mathrm{H} \quad 02 \mathrm{H}$ | 0 | $/$ | time code period mod 65536 lsbyte |
| :--- | :--- | :--- | :--- |
| 1 | $/$ | time code period mod 65536 msbyte |  |
| 2 | $/$ | AUXA1 data byte |  |
|  | 3 | $/$ | AUXA2 data byte |

MINTR0 is cleared by this command.

The time code period and AUX analog data are returned to facilitate data logging applications which use the event strobe.
<Output auxiliary data.>

| $83 \mathrm{H} \quad 03 \mathrm{H}$ | 0 | $/$ | time code period mod 65536 lsb |
| :--- | :--- | :--- | :--- |
|  | 1 | $/$ | time code period mod 65536 msb |
| 2 | $/$ | AUXA1 data byte |  |
|  | 3 | $/$ | AUXA2 data byte |
|  | 4 | $/$ | AGC level |
|  | 5 | $/$ | reserved |
|  | 6 | $/$ | reserved |

## CHAPTER TWO

<Initialization command>
$90 \mathrm{H} \quad 10 \mathrm{H}$
no associated data
<Reset>

91H 10H no associated data

### 2.2 LATENCY

This section summarizes the latency associated with the data request commands listed above. These times have been determined experimentally using an AT class computer equipped with an SBX bus adapter module. Latency is defined as the time between the initiation of a command (writing to offset 07 H ) and the detection of the 'ready flag' (offset 07 H modified by the bc330SBX firmware).

| Command | Typ $(\mu$ sec $)$ | $\operatorname{Max}(\mu$ sec $)$ |
| :---: | :---: | :---: |
| 80 H | 160 | 200 |
| 81 H | 110 | 160 |
| 82 H | 60 | 100 |
| 83 H | 60 | 100 |

## CHAPTER THREE

## DATA AND CONNECTOR ASSIGNMENTS

### 3.0 USING TIME CODE PERIOD DATA

The period of the input time code is provided on response to commands 82 H and 83 H . The return value is the count remaining in a 16 bit counter at the end of a time code second. The counter is reset at the beginning of each detected time code second. If the bc330SBX crystal and the source time code used the same crystal reference, then the return value will be different, reflecting the fact that the two time-bases are not the same. By providing this modulus the bc330SBX allows the user to correct the $0.5 \mu \mathrm{sec}$ count data, and remove the small inaccuracies associated with differing crystal frequencies.

Suppose that the period value returned is 35000 . This value is 1080 greater than 33920 . Furthermore, suppose that the data corresponding to a logged event is returned as follows:


Accurate event logging and current time reporting are maintained during periods of code loss because the bc330SBX continues to update its internal time-base using the drift correction calculated when a time code was present.

### 3.1 SERIAL PORT DATA

The serial output data lines TX(+) and TX(-) may be used to drive both the RS-422 and RS-232-C receiver inputs. The RS-422 connections are simply made according to the respective polarity indicated. An RS-232-C receiver, such as a PC serial input, can be driven by connection TS(-) to the RX input pin. The data pacing signals RTS, CTS, DSR, and DTR may need to be jumpered depending on the specific terminal emulation software in use.

The serial port broadcasts in an ASCII format suitable for direct terminal display. This port is very useful for diagnostic purposes. The bc330SBX broadcasts time, measured code period, code detection status, code search status, software version and date code, AGC slice level, and control byte information over this port. The data stream may easily be parsed for a specific data item.

The serial port parameters are as follows:
9600 baud / 8 data bits / 1 stop bit / no parity

### 3.2 SBX CONNECTOR ASSIGNMENTS (P2)

Table 3-1 summarizes the bc330SBX module SBX bus signal utilization.
Table 3-1
P2 Connector Assignments

| Pin | Mnemonic | Use | Pin | Mnemonic | Use |
| :---: | :--- | :---: | :---: | :--- | :---: |
| 1 | +12 V | N | 2 | -12 V | N |
| 3 | GND | Y | 4 | +5 V | Y |
| 5 | RESET | N | 6 | MCLK | N |
| 7 | MA2 | Y | 8 | MPST $^{*}$ | GND |
| 9 | MA1 | Y | 10 | ----- | N |
| 11 | MA0 | Y | 12 | MINTR1 | GND |
| 13 | IOWRT* | Y | 14 | MINTR0 | Y |
| 15 | IORD* | Y | 16 | MWAIT* | Y |
| 17 | GND | Y | 18 | $+5 \mathrm{~V}^{*}$ | Y |
| 19 | MD7 | Y | 20 | MCS1* | Y |
| 21 | MD6 | Y | 22 | MCS0* | Y |
| 23 | MD5 | Y | 24 | ----- | N |
| 25 | MD4 | Y | 26 | TDMA | N |
| 27 | MD3 | Y | 28 | OPT1 | N |
| 29 | MD2 | Y | 30 | OPT0 | N |
| 31 | MD1 | Y | 32 | MDACK* | N |
| 33 | MD0 | Y | 34 | MDRQT | N |
| 35 | GND | Y | 36 | +5 V | Y |

## CHAPTER FOUR

## ADJUSTMENT

### 4.0 ADJUSTMENT

The bc330SBX has only a single adjustment which should never require alteration by the user. This section outlines a method for correctly setting the value of this adjustment, variable resistor R1. The following steps assume that the bc330SBX is correctly mounted on a baseboard and is exposed to allow access by an oscilloscope probe. A source of IRIG B time code is required.

Select an IRIG B time code by writing a 'B' $(42 \mathrm{H})$ to offset location 08 H . (MCS1* address 0 .) This step forces the bc330SBX to search for a 1000 Hz carrier frequency only.

Input the IRIG B time code to pin \#2 of edge connector P1.

Use pin \#16 of U3 as the input to channel A of a dual channel oscilloscope. Use the reference carrier selected in the above step as the input to channel B of the oscilloscope. Use channel A as the oscilloscope horizontal synch input.

Adjust R1 so that the negative going transitions on pin \#16 are centered on the negative "peaks" of the carrier. See figure 4-1 below.

## Figure 4-1

Phase Lock Loop Adjustment


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## CHAPTER FIVE

DRAWINGS

### 5.0 DRAWINGS

The drawings listed below can be found on the pages following page 6-2.

| Title | Number | Revision |
| :--- | :---: | :---: |
| Assembly bc330SBX Time Code Translator | 11403 | C |
| Schematic Diagram bc330SBX Time Code Translator Module | 11400 | C |

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## CHAPTER SIX

PARTS LIST

### 6.0 PARTS LIST

The parts lists listed below can be found on the pages following page 6-2.

| Title | Number | Revision |
| :---: | :---: | :---: |
| bc330SBX Time Code Translator | bc11403-1000 | D |

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```
ERP 4.01.01 SJ
SJ
DATUM, INC
Item Current Routin
Description Move Hrs Queue Hrs Setup Hrs LbrHrs/PC MchHrs/Pc
Crew Ctl Type Item
M 1708-3518
SOCKET: IC 24P DIP .3C
REF U5
M 1709-0026
CONN: 26P 2X13 EDGE .100C IDC
P1 SEE NOTES
\begin{tabular}{llllllllll}
20 & 327 & OPER.-ELEC/MECH ASSY & 0.00 & 0.00 & 0.00 & 1.000 & 0.000 & \(?\) & \(?\) \\
30452 & PROD. & TEST INSP & 0.00 & 0.00 & 0.00 & 0.000 & 0.000 & \(?\) & \(?\) \\
40 & 400 & TEST & 0.00 & 0.00 & 0.00 & 0.500 & 0.000 & \(?\) & \(?\)
\end{tabular}
```


## NOTES:

```
SEE ASSY. DWG\# 11403C FOR COMPONENT
LOCATION.
hareware instructions:
1. LOCATE HOLE IN PCB BETWEEN C12 \& C14.
INSTALL A \#6-1/4X1/2" NYLON HEX STANOFF
TO BACK SIDE OF PCB USING A \#6X3/16
NYLON SCREW.
2. 1709-0026: NOT INSTALLED UNTILL AFTER TESTING.
MEMORY IC's: THE FOLLOWING MEMORY CHIPS
MUST BE PROGRAMED BEFORE INSTALLATION ON
PC BOARD:
1. 0301-0610-1 EP610 TO U5
ROGRAMIED PER BURN FILE 9520023
2. 0301-27C2-56 27C256 TO U4
PROGRAMIED PER BURN FILE DT10025.
SPECIAL COMPONENT INSTALLATION:
1702-0036 INSTALL TO BACK SIDE OF PCB.
```

